

Doubled Field Theory, T-duality and Courant Brackets

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Lecture 1

Introduction

String theory in toroidal backgrounds

- Generalized metric
- Constraints
- $O(D,D)$ transformations

Introduction

Closed strings on toroidal backgrounds have momentum and winding. The field theory of closed strings is a doubled field theory (DFT)

$$x^i = \{x^a, x^u\}$$

↑ ↴ non-compact
compact

x^a dual to p_a (momentum)

need \tilde{x}_a dual to w^a (winding)

Doubled fields: $\phi(x^a, \tilde{x}_a, x^u)$

Action $S = \int dx^a d\tilde{x}_a dx^u \mathcal{L}(x, \tilde{x}, x^u)$

We will focus on the massless sector of closed strings. The familiar low energy effective field theory is given by

$$S_* = \int dx \sqrt{g} e^{2\phi} [R + 4(\partial\phi)^2 - \frac{1}{12} H^2] \dots$$

fields g_{ij}, b_{ij}, ϕ

What does this become for tori, and doubled fields?

Gauge symmetry parameters are

vector fields ξ^i (diffeomorphism) $\in T(M)$

one-forms $\tilde{\xi}_i$ (b_{ij} gauge tr.) $\in T^*(M)$

$\xi + \tilde{\xi} \in T(M) \oplus T^*(M)$, natural setup of generalized geometry (GG)

In GG the Courant bracket is the right extension of the Lie bracket. How does it show up in DFT?

In string theory the field $\mathcal{E}_{ij} = g_{ij} + b_{ij}$ is natural. How does it show in DFT?

In GG and string theory the generalized metric \mathcal{H}^{MN} is a key structure. How does it show up in DFT?

We will write DFT's that are T-duality covariant versions of S^* . Courant brackets, E_{ij} , H^{MN} , will all play a role. There are still geometrical open questions.

Is there a consistent fully doubled field theory using just $g_{ij}(x, \bar{x})$, $b_{ij}(x, \bar{x})$ and $\phi(x, \bar{x})$? Not clear yet.

References:

Hull and Z. 0904.4664
0908.1792

Hohm, Hull and Z. 1003.5027
1006.4823

Siegel 9305073
9302036

Tseytlin NPB350 (1991) 395

Strings in Toroidal backgrounds

Sigma model action:

$$S = -\frac{1}{4\pi} \int_0^{2\pi} d\sigma \int d\tau \left(-\eta^{\alpha\beta} \partial_\alpha X^i \partial_\beta X^j G_{ij} + \epsilon^{\alpha\beta} \partial_\alpha X^i \partial_\beta X^j B_{ij} \right) \quad (1)$$

$$\eta^{\alpha\beta} = \text{diag}(-1, 1) \quad \epsilon^{01} = -1,$$

$$X^i = \{X^a, X^u\} \quad X^a \sim X^a + 2\pi, \quad i = 0, \dots, D-1$$

$$G_{ij}, B_{ij} \quad D \times D \underset{\text{matrices}}{\text{constant}} \quad G^{ij} G_{jk} = \delta_k^l, \quad X, G, B \text{ are unit-free}$$

$$G_{ij} = \begin{pmatrix} \hat{G}_{ab} & 0 \\ 0 & \eta_{\mu\nu} \end{pmatrix} \quad B_{ij} = \begin{pmatrix} \hat{B}_{ab} & 0 \\ 0 & 0 \end{pmatrix}$$

$$E_{ij} = G_{ij} + B_{ij} = \begin{pmatrix} \hat{E}_{ab} & 0 \\ 0 & \eta_{\mu\nu} \end{pmatrix} \quad \text{with } \hat{E}_{ab} = \hat{G}_{ab} + \hat{B}_{ab}$$

From the action

$$2\pi P_i = G_{ij} \dot{X}^j + B_{ij} X^j \quad (2)$$

$$4\pi \underline{H} = (X', 2\pi P) \mathcal{H}(E) \begin{pmatrix} X' \\ 2\pi P \end{pmatrix} \quad (3)$$

$$\text{with } \mathcal{H}(E) = \begin{pmatrix} G - BG^{-1}B & BG^{-1} \\ -G^{-1}B & G^{-1} \end{pmatrix} \quad (4)$$

2D x 2D
matrix

Exercise 1 Prove (2), (3), (4).

$\mathcal{H}(E)$ is a $2D \times 2D$ symmetric matrix constructed out of G and B . It is called the "generalized metric". More precisely we will identify it with an object \mathcal{H}^{MN} with $M, N = 1, \dots, 2D$

$$\mathcal{H} = \begin{pmatrix} G - BG^{-1}B & BG^{-1} \\ -G^{-1}B & G^{-1} \end{pmatrix} = \begin{pmatrix} 1 & B \\ 0 & 1 \end{pmatrix} \begin{pmatrix} G & 0 \\ 0 & G^{-1} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -B & 1 \end{pmatrix} \quad \dots (5)$$

$$\mathcal{H}^{-1} = \begin{pmatrix} 1 & 0 \\ B & 1 \end{pmatrix} \begin{pmatrix} G^{-1} & 0 \\ 0 & G \end{pmatrix} \begin{pmatrix} 1 & -B \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} G^{-1} & -G^{-1}B \\ BG^{-1} & G - BG^{-1}B \end{pmatrix} \quad \dots (6)$$

It is clearly a reorganization. \leftrightarrow

Define $\eta = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ another metric (symm) (7)

Then $\eta \mathcal{H} \eta = \mathcal{H}^{-1}$ (A constraint) (8)

Let's put indices here $\mathcal{H} \leftrightarrow \mathcal{H}^{MN}$
 $\mathcal{H}^{-1} \leftrightarrow \mathcal{H}_{MN}$

"like for metrics"

⑧ becomes

$$\eta_{PM} \mathcal{H}^{MN} \eta_{NQ} = \mathcal{H}_{PQ}$$

$$\mathcal{H}^{MN} \eta_{MP} \eta_{NQ} = \mathcal{H}_{PQ} \quad \dots \dots \dots (9)$$

Lowering the indices of \mathcal{H} with the η metric gives us the \mathcal{H}^{-1} .

Oscillation expansions $\alpha_n, \tilde{\alpha}_n$ ($x^i = x^i + w^i \sigma + \omega G^{ij} p_j$)⁽⁶⁾

$$\tilde{\alpha}_0^i = \frac{1}{\sqrt{2}} G^{ij} (p_j - E_{kj} w^k)$$

$$\bar{\alpha}_0^i = \frac{1}{\sqrt{2}} G^{ij} (p_j + E_{kj} w^k)$$

$$\alpha_{0i} = -\frac{i}{\sqrt{2}} \left(\frac{\partial}{\partial x^i} - E_{ik} \frac{\partial}{\partial \tilde{x}_k} \right) = -\frac{i}{\sqrt{2}} D_i$$

$$\bar{\alpha}_{0i} = -\frac{i}{\sqrt{2}} \left(\frac{\partial}{\partial x^i} + E_{ki} \frac{\partial}{\partial \tilde{x}_k} \right) = -\frac{i}{\sqrt{2}} \bar{D}_i$$

These are useful derivatives

$D_i = \partial_i - E_{ik} \tilde{\partial}^k$	$D^i = G^{ij} D_j$
$\bar{D}_i = \partial_i + E_{ki} \tilde{\partial}^k$	$\bar{D}^i = G^{ij} \bar{D}_j$

(10)

Note that

$$L_0 = \frac{1}{2} \alpha_0^L G_{ij} \alpha_0^j + N - 1$$

$$\bar{L}_0 = \frac{1}{2} \bar{\alpha}_0^L G_{ij} \bar{\alpha}_0^j + \bar{N} - 1$$

$$L_0 - \bar{L}_0 = N - \bar{N} + \frac{1}{2} \left(-\frac{1}{2} \right) (D^i G_{ij} D^j - \bar{D}^i G_{ij} \bar{D}^j)$$

$$L_0 - \bar{L}_0 = N - \bar{N} - \frac{1}{2} \frac{1}{2} (D^i D_i - \bar{D}^i \bar{D}_i)$$

Exercise 2 Show that

$\frac{1}{2} (D^i D_i - \bar{D}^i \bar{D}_i) = -2 \partial_i \tilde{\partial}^i$	(11)
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Since $L_0 - \bar{L}_0 = 0$ for all states of the theory. 7

$$N - \bar{N} = \frac{1}{2} (-2 \partial_i \tilde{\partial}^i) = -\partial_i \tilde{\partial}^i = -\partial \cdot \tilde{\partial}$$

For the familiar massless fields

$$\int d\mathbf{p} dw \ e_{ij}(\mathbf{p}, w) \ \alpha_{-i}^l \bar{\alpha}_{-i}^j \ c_i \bar{c}_i | \mathbf{p}, w \rangle \quad N = \bar{N} = 0$$

$$\int d\mathbf{p} dw \ d(\mathbf{p}, w) (g_i c_i - \bar{g}_i \bar{c}_i) | \mathbf{p}, w \rangle \quad N = \bar{N} = 0$$

we have $e_{ij}(x, \bar{x})$, $d(x, \bar{x})$ fields.

So we must have

$$\partial \cdot \tilde{\partial} \{ e_{ij}(x, \bar{x}), d(x, \bar{x}) \} = 0 \quad (12)$$

O(D,D) transformations Invariance of the
physics under background transformations.

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From the Hamiltonian density \underline{H} in $^{(3)}$:

$$H = \int_0^{2\pi} d\sigma \underline{H} = \frac{1}{2} \underline{Z}^t H(E) \underline{Z} + N - \bar{N} + \dots \quad (13)$$

$\underline{Z} = \begin{pmatrix} w^i \\ p_i \end{pmatrix}$ 2D column vector with winding
and momentum integer quantum
numbers

$$N - \bar{N} = \frac{1}{2} \underline{Z}^t \eta \underline{Z} \quad \text{Condition on spectrum} \quad (14)$$

Consider a reshuffling of the (w,p) quantum numbers

$$\underline{Z}' = h^t \underline{Z}, \text{ with some } 2D \times 2D \text{ matrix } h$$

Then need

$$\underline{Z}^t \eta \underline{Z}' = \underline{Z}^t \eta \underline{Z} = \underline{Z}'^t h \eta h^t \underline{Z}'$$

which requires

$$h^t \eta h^t = \eta \quad (15)$$

Exercise 3

Show that (15) implies

$$\boxed{h^t \eta h = \eta} \quad \dots \dots \dots \quad (16)$$

h is a $2D \times 2D$ matrix of integers

$h \in O(D,D)$ group

$$h = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad \dots \dots \dots \quad (17)$$

Equation (16) gives

$$\begin{aligned} a^t c + c^t a &= 0, \\ b^t d + d^t b &= 0, \\ a^t d + c^t b &= 1. \end{aligned} \tag{18}$$

Equation (15) gives

$$\begin{aligned} a b^t + b a^t &= 0, \\ c d^t + d c^t &= 0, \\ a d^t + b c^t &= 1. \end{aligned} \tag{19}$$

Exercise 4 Show that $H^{-1} = \begin{pmatrix} d^t & b^t \\ c^t & a^t \end{pmatrix}$. (20)

What more is needed for invariance of the spectrum? From (13):

$$Z^t H(E) Z = Z'^t H(E') Z'$$

$$Z'^t h H(E) h^t Z' = Z'^t H(E') Z'$$

Thus we need

$$\boxed{h^t H(E') h = h H(E) h^t.} \tag{21}$$

Is this possible?

Claim: Letting

$$\boxed{E^t \cdot h(E) = (aE+b)(cE+d)^{-1}} \quad \dots \quad (2)$$

$$= \begin{pmatrix} a & b \\ c & d \end{pmatrix} E \quad (\text{notation!})$$

This will lead to the desired result.

Exercise 5 Show that

$$E^{tt} = \begin{pmatrix} a & -b \\ -c & d \end{pmatrix} E^t \left(\in (aE^t - b)(d - cE^t)^{-1} \right) \quad (3)$$

Back to the claim: Create E from the identity background $E \in \mathbb{I}$

$E = h_E(\mathbb{I})$ what is $h_E \in O(D,D)$?

take $E = G + B$, with $G = AA^t$ (A is like a vierbein)

$$h_E = \begin{pmatrix} A & 'B(A^t)^{-1}' \\ 0 & (A^t)^t \end{pmatrix} ? \quad (24)$$

can verify $h_E \in O(D,D)$

$$\begin{aligned} \text{check it } h_E(\mathbb{I}) &= (A\mathbb{I} + B(A^t)^{-1})(0 \cdot \mathbb{I} + (A^t)^{-1})^{-1} \\ &= (A + B(A^t)^{-1})A^t = AA^t + B = E \checkmark \end{aligned}$$

h_E is ambiguous i.e. $h_E \rightarrow h_E \cdot g$

$$\text{where } g(\mathbb{I}) = \mathbb{I} \quad \text{if } g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow a+b=c+d$$

but: consider also "that" $\bar{g}(\mathbb{I}) = \mathbb{I}$

Exercise 6

Show that the elements g that satisfy
 $g(I) = I$ form an $O(D) \times O(D)$ subgroup of $O(D, D)$
and $g^t g = g g^t = I$

Now let $E' = h(E)$

$$\rightarrow h_{E'}(I) = h h_E(I)$$

$$h_{E'} = h h_E g \quad g \in O(D) \times O(D); \quad g^t g = g g^t = I$$

Now calculate $h_E h_E^t$

$$\begin{aligned} h_E h_E^t &= \begin{pmatrix} A & BA^{t-1} \\ 0 & (A^t)^{-1} \end{pmatrix} \begin{pmatrix} A^t & 0 \\ -A^{-1}B & A^{-1} \end{pmatrix} \quad G = AA^t \\ &= \begin{pmatrix} AA^t - BA^{t-1}A^{-1}B & BA^{t-1}A^{-1} \\ -(A^t)^{-1}A^{-1}B & (A^t)^{-1}A^{-1} \end{pmatrix} \quad G^{-1} = A^{t-1}A^{-1} \\ &= \begin{pmatrix} G - BG^{-1}B & BG^{-1} \\ -G^{-1}B & G^{-1} \end{pmatrix} = H(E) \end{aligned}$$

$$\text{So } H(E) = h_E h_E^t \quad \dots \quad (25)$$

$$H(E') = h_{E'} h_{E'}^t = h h_E g (h h_E g)^t$$

$$= h h_E h_E^t h^t = h H(E) h^t$$

this proves (2).

How are G and G' related?

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Exercise 7 Prove that

$$\boxed{(d + cE)^t G' (d + cE) = G} \quad \dots \quad (26)$$

Hint: write $G' = \frac{E' + E'^t}{2}$, use (22) and evaluate the LHS.

Prove that:

$$\boxed{(d - cE^t)^t G' (d - cE^t) = G} \quad \dots \quad (27)$$

Use (23) and write $G' = \frac{(E')^t + (E')^t}{2}$.

Define

$$M \equiv (d - cE^t)^t,$$

$$\bar{M} \equiv (d + cE)^t.$$

Then (26), (27) become

$$G = \bar{M} G' M^t, \quad (28)$$

$$G = M G' \bar{M}^t.$$

Examples of $O(DD)$ "tensors"

$$G_{\bar{i}\bar{j}} = \bar{M}_i{}^{\bar{P}} \bar{M}_j{}^{\bar{q}} G'_{\bar{P}\bar{q}}, \quad (29)$$

$$G_{ij} = M_i{}^p M_j{}^q G'_{pq},$$

bared and unbared indices.

Relating the fundamental $\Theta = \begin{pmatrix} \tilde{\theta}_i \\ \theta_i \end{pmatrix}$ of O(DD)¹³ to these levers:

$$\begin{pmatrix} \tilde{\theta}' \\ \theta' \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} \tilde{\theta} \\ \theta \end{pmatrix} \quad \text{Definition of fundamental (30)}$$

$$Y_i = -\tilde{\theta}_i + E_{ij} \theta^j \quad (Y = -\tilde{\theta} + E\theta) \quad (31)$$

$$\bar{Y}_i = \tilde{\theta}_i + \bar{E}_{ij} \theta^j \quad (\bar{Y} = \tilde{\theta} + \bar{E}^t \theta)$$

Then

$$Y_i = M_i^j Y_j, \quad \dots \dots \dots \quad (32)$$

$$Y_i = \bar{M}_i^j \bar{Y}_j.$$

Exercise 8: Prove the 1st of (32).

For this you will need the identity:

$$b^t - E a^t = -M E^t, \text{ move it!} \quad \dots \dots \quad (33)$$

Application $X^M = \begin{pmatrix} \tilde{x}_i \\ x^i \end{pmatrix}$ is in the fundamental,

partial derivatives $\partial_M = \begin{pmatrix} \tilde{\partial}^i \\ \partial_i \end{pmatrix}$.

$$\rightarrow \partial^M = \gamma^{MN} \partial_N X^i = \begin{pmatrix} \partial_i \\ \tilde{\partial}^i \end{pmatrix} \quad \text{also in the fund.}$$

Note $\partial^M \partial_M = 2 \partial_i \tilde{\partial}^i = 0$ is our constraint

$$-\partial_i + E_j \tilde{\partial}^j = -D_i \quad \text{our "derivatives"}$$

$$\partial_i + E_{ji} \tilde{\partial}^j = \bar{D}_i$$

Transform covariantly!

$$D_i = M_i^j D'_j \quad (DF(x') = M D' F(x'))$$

$$\bar{D}_i = \bar{M}_i^j \bar{D}'_j \quad (34)$$

E is not a tensor, but its variation is!

Let $E' = h(E)$, then

$$\begin{aligned} E' + \delta E' &= h(E + \delta E) \\ &= (a(E + \delta E) + b)(c(E + \delta E) + d)^{-1} \\ &= (aE + b + a\delta E)(cE + d + c\delta E)^{-1} \end{aligned}$$

**

$$= (aE + b + a\delta E)((cE + d)^{-1} - (cE + d)^{-1} c\delta E (cE + d)^{-1})$$

$$= E' + a\delta E (cE + d)^{-1} - E' c \delta E (cE + d)^{-1}$$

$$\rightarrow \delta E' = (a - E' c) \delta E (\bar{M}^t)^{-1} \quad (35)$$

$$** (A + \epsilon)^{-1} = A^{-1} - A^{-1} \epsilon A^{-1}$$

Now claim that

$$a - E'c = M^{-1} \quad \dots \quad (35)$$

Indeed multiply by M from the left

$$M(a - E'c) \stackrel{?}{=} 1$$

$$Ma - \underline{ME'c} \stackrel{?}{=} 1 \quad \text{use (33)}$$

$$(dt - E^t a) + (bt - E^t c) \stackrel{?}{=} 1$$

$$\underbrace{dt a + bt c}_{1} - E(\underbrace{ct a + a^t c}_0) \stackrel{?}{=} 1 \quad \checkmark$$

therefore; back in (35)

$$\begin{aligned} \delta E' &= M^{-1} \delta E (\bar{M}^t)^{-1} \\ \Rightarrow \delta E &= M \delta E' \bar{M}^t \end{aligned} \quad \dots \quad (37)$$

$$\boxed{\delta E_j = M_{jl} \bar{m}_l \delta E'_{lk}} \quad \dots \quad (37) \quad \text{A tensor!}$$

This applies to any derivative

$$\partial_i E = M \partial_i E' \bar{M}^t \quad (38)$$

$$\tilde{\partial}^i E = M \tilde{\partial}^i E' \bar{M}^t$$

and then

$$D_i E = M D_i E' \bar{M}^t \quad \bar{D}_i E = M \bar{D}_i E' \bar{M}^t \quad (39)$$

so $D_i E_{jk}, \bar{D}_i E_{jk}$ are tensors!!

(40)

Lecture 2

Free doubled field theory

Aspects of interactions

Strong constraint.

Covariant brackets

Gauge algebra

Free theory: background E_{ij} , fields e_i, d

$$S^{(2)} = \int dx d\tilde{x} \left[\frac{1}{4} e^{ij} \square e_{ij} + \frac{1}{4} (\bar{D}^j e_{ij})^2 + \frac{1}{2} (D^i e_{ij})^2 - 2d D^i \bar{D}^j e_{ij} - 4d \square d \right] \quad (41)$$

Indices raised by G^{ij} , $\square = D^i D_i = \bar{D}^i \bar{D}_i$

constraint $D^2 - \bar{D}^2 = 0 \Leftrightarrow \partial \cdot \bar{\partial} = 0$
on fields and gauge parameters

Exercise 9 Prove that the following are
gauge invariances of $S^{(2)}$:

$$\delta e_{ij} = \bar{D}_j \lambda_i, \quad (42)$$

$$\delta d = -\frac{1}{4} D \cdot \lambda.$$

In fact there are also the gauge invariances:

$$\delta e_i = D_i \bar{\lambda}, \quad (43)$$

$$\delta d = -\frac{1}{4} \bar{D} \cdot \bar{\lambda}.$$

Assume $B = 0$,

What does the $S^{(2)}$ become?

$$\begin{aligned}
 S^{(2)} = \int dxd\tilde{x} & \left[\frac{1}{4} h^0 \partial^2 h_{ij} + \frac{1}{2} (\partial^i h_{ij})^2 - 2d\partial^i \partial^j h_{ij} - 4d\partial^2 d \right. \\
 & + \frac{1}{4} h^0 \tilde{\partial}^2 h_{ij} + \frac{1}{2} (\tilde{\partial}^i h_{ij})^2 + 2d\tilde{\partial}^i \tilde{\partial}^j h_{ij} - 4d\tilde{\partial}^2 d \\
 & + \frac{1}{4} b^0 \partial^2 b_{ij} + \frac{1}{2} (\partial^i b_{ij})^2 \\
 & + \frac{1}{4} b^0 \tilde{\partial}^2 b_{ij} + \frac{1}{2} (\tilde{\partial}^i b_{ij})^2 \\
 & \left. + (\partial_k h^{ik})(\tilde{\partial}^j b_{ij}) + (\tilde{\partial}^k h_{ik})(\partial^j b_{ij}) - 4d\partial^i \tilde{\partial}^j b_{ij} \right] \tag{44}
 \end{aligned}$$

The gauge parameters are redefined;

$$\epsilon_i = \frac{1}{2}(\lambda_i + \bar{\lambda}_i) \quad \tilde{\epsilon}_i = \frac{1}{2}(\lambda_i - \bar{\lambda}_i) \tag{45}$$

Then

$$\begin{aligned}
 \delta h_{ij} &= \partial_i \epsilon_j + \partial_j \epsilon_i, \\
 \delta b_{ij} &= -(\tilde{\partial}_i \epsilon_j - \tilde{\partial}_j \epsilon_i), \\
 \delta d &= -\frac{1}{2} \partial \cdot \epsilon \quad \Phi \equiv d + \frac{h}{4}, \quad \delta \Phi = 0
 \end{aligned} \tag{46}$$

$$\begin{aligned}
 \tilde{\delta} h_{ij} &= \tilde{\partial}_i \tilde{\epsilon}_j + \tilde{\partial}_j \tilde{\epsilon}_i, \\
 \tilde{\delta} b_{ij} &= -(\partial_i \tilde{\epsilon}_j - \partial_j \tilde{\epsilon}_i)
 \end{aligned} \tag{47}$$

$$\tilde{\delta} d = \frac{1}{2} \tilde{\partial} \cdot \tilde{\epsilon} \quad \tilde{\Phi} = d - \frac{h}{4} \quad \tilde{\delta} \tilde{\Phi} = 0$$

no scalar dilaton !!

$O(D,D)$ covariance of the theory in (41)

e_{ij} is an $O(D,D)$ tensor, so are D_i, \bar{D}_j and $g^{ij} (\equiv g^{\bar{i}\bar{j}})$. Since all indices are contracted properly the action is invariant.

Cubic terms exist consistent with a nonlinear extension of the gauge invariance

$$S^{(3)} = \int dxd\bar{x} \left[\frac{1}{4} e_{ij} (D^l e_{jk}) (\bar{D}^{\bar{l}} \bar{e}^{\bar{k}}) - D^l e_{jk} \bar{D}^{\bar{l}} \bar{e}^{\bar{k}} - D^k e_{jl} \bar{D}^l \bar{e}_{\bar{k}} \right] + d^2 e^2 \text{ terms} + d^2 \bar{e} \text{ terms} + d^3 \text{ term.} \quad (48)$$

$$\delta_\lambda e_{ij} = \bar{D}_j \lambda_i + \frac{1}{2} \left[(D_i \lambda^k) e_{kj} - (D^k \lambda_i) e_{kj} + \lambda_k D^k e_{ij} \right] \quad (49)$$

↑
products projected to the kernel of $\partial \bar{\partial}$

Construction to higher orders may be very nontrivial, or may not exist
(keeping only e_{ij}, d)

Options:

- * Continue the construction to higher order
- * Extract lessons so far.

So far all fields or gauge parameters

A_1, A_2, A_3, \dots are killed by $\partial_\mu \partial^M$.

Require now that all products $A_i A_j$ be killed by $\partial_\mu \partial^M$.

$$\partial_M \partial^M (A_i A_j) = 0 \rightarrow \boxed{\partial_M A_i \partial^M A_j = 0} \quad (50)$$

$O(D,D)$ "strong" constraint: all fields and all products are killed by $\partial \cdot \tilde{\partial}$.

Theorem: For a set of fields $A_i(x, \tilde{x})$ that satisfy

(50) there is a duality frame (\tilde{x}'^l, x^l) in which the fields do not depend on \tilde{x}'^l .

\tilde{x}'^l

The duality frame need not be specified explicitly, the constraint (50) does not break $O(D,D)$ and can be imposed without selecting frames.

The resulting theory will have $O(D,D)$ symmetry, will involve x, \tilde{x} , but it is an $O(D,D)$ covariantization of a theory that in some dual frame is not doubled.
(close relation to Siegel)

The theory can be constructed explicitly

- * It shows an interplay of $O(D,D)$ with gauge invariance.
- * The gauge algebra will be novel:
Courant bracket !!
- * The action can be background independent and duality invariant.
- * The Action can be written in terms of the generalized metric

→ let us begin by considering
Courant brackets!

Covariant brackets

In a theory with a metric $g_{ij}(x)$ and a KR field $b_{ij}(x)$ the symmetries are diffeomorphisms generated by vector fields $V^i(x)$ and KR gauge transformations generated by one-forms $\xi_i(x)$

$$V \in T(M), \quad \xi \in T^*(M), \quad \text{formally} \\ V + \xi \in T(M) \oplus T^*(M)$$

What are the gauge transformations?

$$\delta_{V+\xi} g = L_V g, \quad \dots \quad (51)$$

$$\delta_{V+\xi} b = L_V b + d\xi.$$

$$\text{Recall that on forms } L_V = i_V d + d i_V, \quad \dots \quad (52)$$

$$\text{on } g \quad \text{so that } L_V d = d L_V, \quad \dots \quad (53)$$

On the metric:

$$L_V g_{ij} = (\partial_i V^k) g_{kj} + \partial_j V^k g_{ik} + V^k \partial_k g_{ij}.$$

On any tensor or form

$$[L_X, L_Y] = L_{[X, Y]} \quad \dots \quad (54)$$

$$[L_X, i_Y] = i_{[X, Y]} \quad \dots \quad (55)$$

$$[X, Y]^k = X^\rho \partial_\rho Y^k \\ \uparrow = Y^\rho \partial_\rho X^k \\ \text{Lie bracket of vectors}$$

Compute the algebra of gauge transf.:

$$\begin{aligned}
 [\delta_{V_2 + \xi_2}, \delta_{V_1 + \xi_1}] g &= \delta_{V_2 + \xi_2} \delta_{V_1 + \xi_1} g - (1,2) \\
 &= \delta_{V_2 + \xi_2} L_{V_1} g - (1,2) \\
 &= L_{V_1} L_{V_2} g - (1,2) \\
 &= L_{[V_1, V_2]} g \quad \dots \dots \dots (56)
 \end{aligned}$$

On b it is more nontrivial

$$\begin{aligned}
 [\delta_{V_2 + \xi_2}, \delta_{V_1 + \xi_1}] b &= \delta_{V_2 + \xi_2} (L_{V_1} b + d\xi_1) - (1,2) \\
 &= L_{V_1} (L_{V_2} b + d\xi_2) - (1,2) \\
 &= L_{[V_1, V_2]} b + d(L_{V_1} \xi_2 - L_{V_2} \xi_1) \\
 &\quad \dots \dots \dots (57)
 \end{aligned}$$

Compare with (51) and conclude that

$$[\delta_{V_2 + \xi_2}, \delta_{V_1 + \xi_1}] = \underbrace{\delta_{[V_1, V_2]} + L_{V_1} \xi_2 - L_{V_2} \xi_1}_{\text{defines a bracket}}$$

$$[V_1 + \xi_1, V_2 + \xi_2] = [V_1, V_2] + L_{V_1} \xi_2 - L_{V_2} \xi_1 \quad \dots \dots \dots (58)$$

Gauge algebra defined by this bracket (?)

Jacobi identity is satisfied $[[t]] + w_C = 0$

There is an ambiguity, however, in reading the one-form since generally,

$$\begin{aligned} S_{V+\xi} b &= L_V b + d\xi \\ &= L_V(\xi + d\sigma). \quad \dots \quad (59) \end{aligned}$$

The 1-form ξ is ambiguous up to $d\sigma$.

"Symmetry for a symmetry"

Thus reading the one-form from (57) is ambiguous.

$$\begin{aligned} &d(L_{V_1}\xi_2 - (12)) \\ &= d(dL_{V_1}\xi_2 + L_{V_1}d\xi_2 - (12)) \\ &\quad \downarrow \\ &\text{change this coefficient } 1 \rightarrow 1 - \frac{\beta}{2} \\ &= d((1 - \frac{\beta}{2})dL_{V_1}\xi_2 + L_{V_1}d\xi_2 - (12)) \\ &= d(L_{V_1}\xi_2 - \frac{1}{2}\beta dL_{V_1}\xi_2 - (12)) \\ &= d(L_{V_1}\xi_2 - L_{V_2}\xi_1 - \frac{1}{2}\beta d(L_{V_1}\xi_2 - L_{V_2}\xi_1)). \\ &\rightarrow \text{generic bracket} \end{aligned}$$

$$\begin{aligned} [V_1 + \xi_1, V_2 + \xi_2] &= [V_1, V_2] + L_{V_1}\xi_2 - L_{V_2}\xi_1 \\ &\quad - \frac{1}{2}\beta d(L_{V_1}\xi_2 - L_{V_2}\xi_1) \quad \dots \quad (60) \end{aligned}$$

Unavoidable ambiguity $\beta \neq 0 \rightarrow$ Failure of Jacobi

T. Courant, 1990 $\beta=1$

$$[v_1 + \xi_1, v_2 + \xi_2] = [v_1, v_2]$$

$$\begin{aligned} &+ \mathcal{L}_{V_1} \xi_2 - \mathcal{L}_{V_2} \xi_1 \\ &- \frac{1}{2} d \cdot (i_{V_1} \xi_2 - i_{V_2} \xi_1) \quad \dots \dots (61) \end{aligned}$$

Jacobi identity does not hold.

$$z_1 = v_1 + \xi_1 \quad z_2 = v_2 + \xi_2 \quad z_3 = v_3 + \xi_3$$

$$[z_1, [z_2, z_3]] + \text{cyclic} = dN(z_1, z_2, z_3)$$

exact 1-form

What is special for $\beta=1$?

There is an automorphism of the bracket, called B-transformation. Given a closed 2-form B ($dB=0$)

$$\text{Btransf: } X + \xi \rightarrow X + (\xi + \iota_X B) \quad \dots \dots (62)$$

changes the 1-form

Autom. means

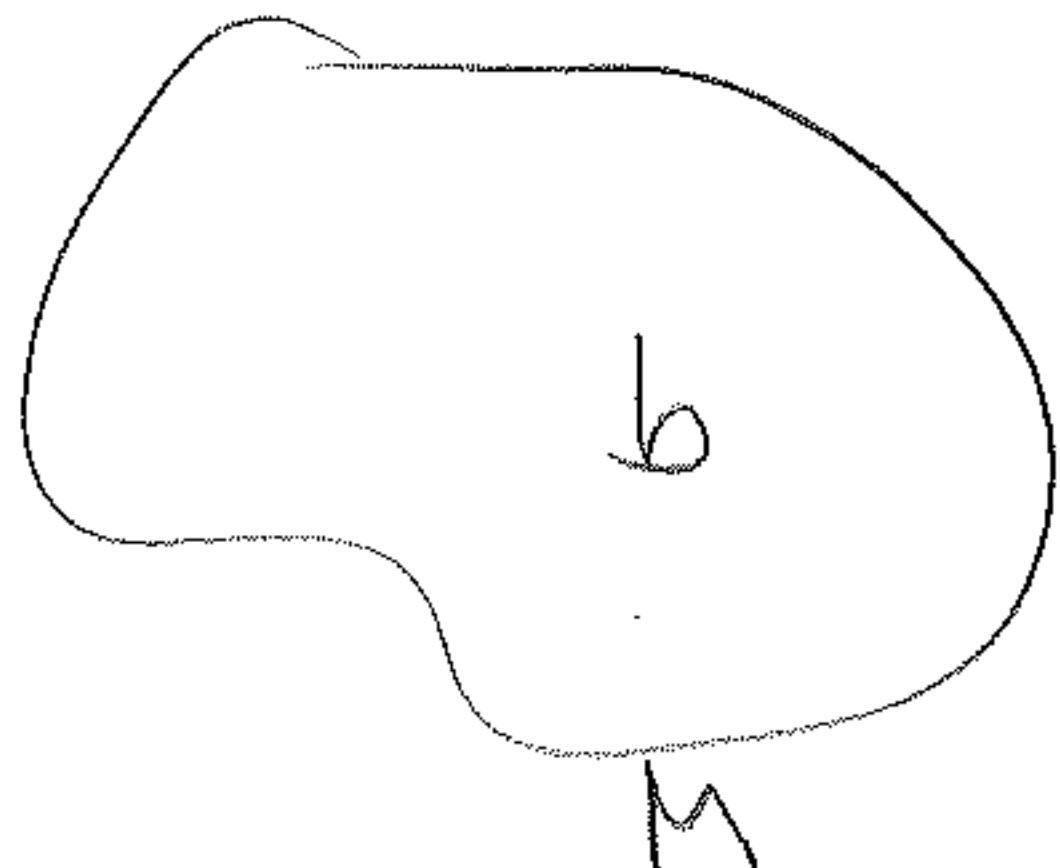
$$[X + \xi + \iota_X B, Y + \eta + \iota_Y B] = [X + \xi, Y + \eta] + [\iota_{[X, Y]} B] \quad \dots \dots (63)$$

Exercise 10 Show that the existence of this automorphism selects $\beta=1$ in (60), thus giving (61).

Why was this a natural thing to require,
for a mathematician?

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Consider the symmetry of b-fields on a manifold M



$$\begin{array}{|l} \text{V} + \underline{\xi} \text{ is a symmetry of } b \\ \hline \end{array}$$

$$\Leftrightarrow \underline{L_V} b = d\underline{\xi}$$

(64)

Consider a 2-form B with $dB = 0$

Claim that the B transform of $\text{V} + \underline{\xi}$
is a symmetry of $b + B$

$$\begin{array}{|l} \text{V} + (\underline{\xi} + i_V B) \text{ is a symmetry of } b + B \\ \hline \end{array}$$

(65)

Verify:

$$\begin{aligned} \underline{L_V} (b + B) &= \underline{L_V} b + (\text{div}_V + i_V \delta) B \\ &= d\underline{\xi} + \text{div}_V B \\ &= d(\underline{\xi} + i_V B) \end{aligned} \quad \dots \quad (66)$$

B transformations (changes of b) do
not change the symmetries of the theory
 \rightarrow promote them to automorphisms

What is the gauge algebra in the strongly constrained theory?

As will be derived later, ...

$$\xi^M = \begin{pmatrix} \tilde{\xi}_1 \\ \tilde{\xi}_2 \end{pmatrix} \quad \text{assemble gauge parameters} \quad (67)$$

The gauge algebra governed by a C-bracket $[\cdot, \cdot]_C$

$$([\xi_1, \xi_2]_C)^M = \xi_1^P \partial_P \xi_2^M - \frac{1}{2} \eta^{MN} \eta_{PQ} \xi_1^P \partial_N \xi_2^Q \quad (68)$$

$$= \xi_{[1} \cdot \partial \xi_{2]}^M - \frac{1}{2} \xi_{P[1} \partial^M \xi_{2]}^P$$

Writing $\xi^M \sim \xi_1 + \tilde{\xi}_1$ in the GG language

$$\begin{aligned} [\xi_1 + \tilde{\xi}_1, \xi_2 + \tilde{\xi}_2] &= [\xi_1, \xi_2] + \mathcal{L}_{\tilde{\xi}_1} \xi_2 - \mathcal{L}_{\tilde{\xi}_2} \xi_1 \\ &\quad - \frac{1}{2} \tilde{d} (\tilde{\mathcal{L}}_{\tilde{\xi}_1} \xi_2 - \tilde{\mathcal{L}}_{\tilde{\xi}_2} \xi_1) \\ &\quad + [\tilde{\xi}_1, \tilde{\xi}_2] + \mathcal{L}_{\tilde{\xi}_1} \tilde{\xi}_2 - \mathcal{L}_{\tilde{\xi}_2} \tilde{\xi}_1 \\ &\quad - \frac{1}{2} d (\mathcal{L}_{\xi_1} \tilde{\xi}_2 - \mathcal{L}_{\xi_2} \tilde{\xi}_1) \quad \dots (69) \end{aligned}$$

$$[\tilde{\xi}_1, \tilde{\xi}_2]_j = \tilde{\xi}_{1i} \tilde{\partial}^i \tilde{\xi}_{2j} - (1,2) \quad \tilde{\partial} f = \tilde{\partial}^i f (dx_i)$$

(69) is a Courant bracket on a
Lie bi-algebroid.

What happens if the gauge parameters
are independent of \tilde{x}

$$\text{then } \mathcal{L}_{\tilde{\xi}} \rightarrow 0 \quad \tilde{\delta} \rightarrow 0 \quad [\tilde{\xi}, \tilde{\xi}] \rightarrow 0$$

and get

$$[\xi_1 + \tilde{\xi}_1, \xi_2 + \tilde{\xi}_2] = [\xi_1, \xi_2] + \mathcal{L}_{\xi_1} \tilde{\xi}_2 - \mathcal{L}_{\xi_2} \tilde{\xi}_1 - \frac{1}{2} d(i_{\xi_1} \tilde{\xi}_2 - i_{\xi_2} \tilde{\xi}_1) \quad (70)$$

the Courant bracket!

Comment: the β -parameter would break
the $O(D,D)$ covariance of the C-bracket

$$[\xi_1, \xi_2]^M = \dots + \left(\frac{\beta-1}{4}\right) \partial^M (\Omega_{PQ} \xi_1^P \xi_2^Q)$$

$$\text{with } \Omega_{PQ} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

\uparrow
not an $O(D,D)$
invariant tensor

What are the B-transformations?

$$h = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix} \quad b \text{ antisymmetric, constant}$$

$$E' = h(E) = (E + b)(1)^{-1} = E + b$$

So indeed

$$B \rightarrow B + b$$

How does it act on gauge parameters $\xi^M = \begin{pmatrix} \tilde{\xi}_1 \\ \xi^2 \end{pmatrix}$

$$\begin{pmatrix} \tilde{\xi}_1 \\ \xi^2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \tilde{\xi}_1 \\ \xi^2 \end{pmatrix}$$

$$\xi \rightarrow \xi$$

$$\xi + \tilde{\xi} \rightarrow \xi + \tilde{\xi} + b\tilde{\xi}$$

$$\tilde{\xi} \rightarrow \tilde{\xi} + b\xi$$

$$\tilde{\partial} \rightarrow \tilde{\partial} \quad \text{fields remain restricted}$$

The B-transformations of the mathematical have a counterpart in part of the T-duality group. T-duality invariance thus bump in the Courant bracket.

Lecture 3

29.

Passing from E_{ij} to \tilde{E}_{ij}

Action in terms of E_{ij}, d .

Duality invariance

Gauge invariance

Action in terms of the Generalized metric

Generalized Lie derivatives

Gauge algebra

Curvature scalar

In the perturbative action above we had
 a background E_{ij} , constant, (and "a fluctuation")
 $e_{ij}(x, \tilde{x})$. Just like for $g_{ij} = \eta_{ij} + h_{ij}$ in relativity,
 one suspects that the action constructed earlier
 could be rewritten in terms of

$$\tilde{E}_{ij}(x, \tilde{x}) = E_{ij} + e_{ij}(x, \tilde{x}) + \Theta(e_{ij}^2(x, \tilde{x})) \quad (71)$$

$$E_{ij}(x) = E_{ij} + e_{ij}(x) + \dots$$

$$X^M = \begin{pmatrix} \tilde{x}_i \\ x^i \end{pmatrix}$$

What could be duality $X \rightarrow X' = \begin{pmatrix} ab \\ cd \end{pmatrix} X$

$$\begin{aligned} \tilde{e}'(x') &= (a\tilde{e}(x) + b)(c\tilde{e}(x) + d)^{-1} \\ d'(x') &= d(x) \end{aligned} \quad (72)$$

The derivatives in (10)

$$\begin{aligned} D_i &= \partial_i - E_{ik} \tilde{\partial}^k \rightarrow D_i = \partial_i - E_{ik}(x) \tilde{\partial}^k \\ \bar{D}_i &= \partial_i + E_{ki} \tilde{\partial}^k \rightarrow \bar{D}_i = \partial_i + e_{ki}(x) \tilde{\partial}^k \end{aligned} \quad (73)$$

All we learned about
 $O(D,D)$ transformations remains true

$$E_{ij} = g_{ij} + b_{ij}$$

$$\text{From (4)} \quad H(E) = \begin{pmatrix} g - bg^{-1}b & bg^{-1} \\ -g^{-1}b & g^{-1} \end{pmatrix} = H^{MN}(E) \quad (74)$$

$$\begin{aligned} M &= (d - CE)^t \rightarrow M(x) = (d - C\epsilon^t)^t \\ \bar{M} &= (d + CE)^t \rightarrow \bar{M}(x) = (d + C\epsilon)^t \end{aligned} \quad (75)$$

g is an $O(D,D)$ tensor, from (28)

$$g(x) = \bar{M}(x) g'(x') \bar{M}^t(x) \quad (76)$$

$$g(x) = M(x) g'(x') M^t(x)$$

(21) becomes

$$H(E'(x')) = h H(E(x)) h^t \quad (77)$$

(34) becomes

$$D_i = M_i^j(x) D_j' \quad (78)$$

(37) becomes

$$\delta E(x) = M(x) \delta E' \bar{M}^t(x) \quad (79)$$

$$\bar{D}_i = \bar{M}_i^j(x) \bar{D}_j'$$

From (4b) $D_i \epsilon_{jk}$, $\bar{D}_i \epsilon_{jk}$ are tensors!

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Transformation of the dilation under gauge transformation

$$\delta d = -\frac{1}{2} \partial_M \xi^M + \xi^M \partial_M d \quad \xi^M = \begin{pmatrix} \tilde{\xi}_1 \\ \xi_i \end{pmatrix} \quad (80)$$

This implies

$$\delta e^{-2d} = \partial_M [\xi^M e^{-2d}] \quad (81) \quad e^{-2d} \text{ is a density}$$

it is identified with
 $\sqrt{g} e^{-2\phi}$

$$S_{e,d} = \int dx d\tilde{x} e^{-2d} \left[-\frac{1}{4} g^{kl} g^{ij} D^P E_{kl} D_P E_{ij} \right. \\ \left. + \frac{1}{4} g^{kl} (D^i E_{ik} D^j E_{jl} + \bar{D}^i E_{ki} \bar{D}^j E_{lj}) \right] \quad (82)$$

$$+ (D^i d \bar{D}^j E_{ij} + \bar{D}^i d D^j E_{ij}) + 4 D^i d D^j d \left. \right]$$

Each term independently O(D,D) invariant

Expanding about E reproduces $S_{e,d}^{(2)} + S_{e,d}^{(3)}$ given before. No O(D,D) invariant term (with two derivatives) can be added to $S_{e,d}$ without spoiling this agreement.

Taking $\tilde{D} = \delta^{ab} D_a D_b$, $S_{e,d}$ reduces to an action that is identical to S_* (p. 2) when $\sqrt{g} e^{-2\phi} = e^{-2d}$!

Gauge transformations

$$\delta_g E_{ij} = \partial_i \tilde{\xi}_j - \partial_j \tilde{\xi}_i \\ + L_g E_{ij} + L_{\tilde{g}} E_{ij} \\ - E_{ik} (\tilde{\partial}^k g^l - \tilde{\partial}^l g^k) E_{lj} \quad (83)$$

Proving directly the gauge invariance is hard.

Formulation with Generalized Metric:

Recall constraint $\partial^M A \partial_M B = 0 \quad \forall A, B$

(of course $\partial^M \partial_M A = \partial^M \partial_M B = 0$)

$$X' = h X \rightarrow X^M = h^M{}_N X^N \text{ with indices}$$

from $\mathcal{H}(E') = h \mathcal{H}(E) h^\dagger$

$$\rightarrow \mathcal{H}(E')^{MN} = h^M{}_P h^N{}_Q \mathcal{H}^{PQ}(E) \quad (84)$$

How about $h^\dagger \eta h = \eta$?

$$h^M{}_P h^N{}_Q \eta_{MN} = \eta_{PQ} \quad (85) \quad (\text{invariant tensor})$$

- noise Q

$$h^M{}_P h_M{}^Q = \delta_P^Q \quad (86)$$

For a lowered indexed object:

$$(87) \quad Y_M^I = h_M{}^P Y_P^I \quad ; \quad h_M{}^P = \eta_{MN} h^N{}_R \eta^{RP}$$

Indeed,

$$X'^M Y_M^I = \underbrace{h^M{}_N h_N{}^P}_{\delta_N^P} X^N Y_P^I = \delta_N^P X^N Y_P^I = X^P Y_P^I.$$

Index contraction is O(DD) invariant.

Recall (8), (9) $\eta \mathcal{H} \eta = \mathcal{H}^\dagger$

$$(88) \quad \mathcal{H}^{MN} \eta_{MP} \mathcal{H}_{NQ} = \mathcal{H}_{PQ} \quad (\mathcal{H}^{PM} \mathcal{H}_{MQ} = \delta_Q^P)$$

$$\begin{aligned}
 S_H = & \int d\tilde{x} d\tilde{x} e^{-2d} \left(\frac{1}{8} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_N \mathcal{H}_{KL} \right. \\
 & - \frac{1}{2} \mathcal{H}^{MN} \partial_N \mathcal{H}^{KL} \partial_L \mathcal{H}_{MK} \\
 & - 2 \partial_M d \partial_N \mathcal{H}^{MN} \\
 & \left. + 4 \mathcal{H}^{MN} \partial_M d \partial_N d \right). \quad (89)
 \end{aligned}$$

How do we write the gauge symmetry?

Conventional Lie derivatives L_ξ

$$L_\xi A_M = \xi^P \partial_P A_M + \partial_M \xi^P A_P, \quad (90)$$

$$L_\xi B^N = \xi^P \partial_P B^N - \partial_P \xi^N B^P. \quad (91)$$

Generalized Lie derivatives \hat{L}

$$\hat{L}_\xi A_M = \xi^P \partial_P A_M + (\partial_M \xi^P - \partial_P \xi_M) A_P, \quad (92)$$

$$\hat{L}_\xi B^N = \xi^P \partial_P B^N - (\partial_P \xi^N - \partial_N \xi_P) B^P. \quad (93)$$

with the help of the η^{MN} we have introduced a new term (each index is transformed covariantly plus contravariantly).

What changes? Our theory has redundant gauge symmetries

$$\xi^M = \partial^M \chi, \quad (94)$$

$$\begin{pmatrix} \tilde{\xi}_i \\ \xi^i \end{pmatrix} = \begin{pmatrix} \partial_i \chi' \\ \tilde{\partial}^i \chi \end{pmatrix}, \quad \text{should not generate gauge transformations}$$

$$\hat{L}_{g=\partial x} A_M = \cancel{\partial^P x \partial_P A_M} + \partial_M (\partial^P x) A_P{}^N \neq 0$$

$$\hat{L}_{g=\partial x} A_M = \partial^P x \partial_P A_M + (\underbrace{\partial_M \partial^P x - \partial^P \partial_M x}_0) A_P = 0 !$$

Nice, generalized Lie derivatives
generate no transformations for "trivial
gauge symmetries"

$$\hat{L}_{g=\partial x} = 0 \quad (95)$$

The gauge symmetry of S_{ft} is:

$$\boxed{\delta \mathcal{H}^{MN} = \hat{L}_{g=\partial x} \mathcal{H}^{MN}} \quad (96)$$

$$\delta e^{-2d} = \partial_M [e^M e^{-2d}] \quad \text{vanishes for } \varepsilon^M = \partial^M x \quad (97)$$

What is the algebra of Generalized \hat{L}_g ?

Claim:

$$[\hat{L}_{\varepsilon_1}, \hat{L}_{\varepsilon_2}] = - \hat{L}_{[\varepsilon_1, \varepsilon_2]_C} \quad ! \quad (98)$$

Exercise 11

Use (92) to prove (98) when acting on A_M

$$[\hat{L}_{\varepsilon_1}, \hat{L}_{\varepsilon_2}] A_M = \dots = - \hat{L}_{[\varepsilon_1, \varepsilon_2]_C} A_M !$$

Not too hard to verify that

$L_{e,d} \equiv L_{\partial x}$ equality of
lagrangians

Is there a generalized Scalar curvature ??

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Yes! It is R , with:

$$\begin{aligned} R = & 4 \mathcal{H}^{MN} \partial_M \partial_N d - \partial_M \partial_N \mathcal{H}^{MN} \\ & - 4 \mathcal{H}^{MN} \partial_M d \partial_N d + 4 \partial_M \mathcal{H}^{MN} \partial_N d \\ & + \frac{1}{8} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_N \mathcal{H}_{KL} \\ & - \frac{1}{2} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_K \mathcal{H}_{NL}. \end{aligned}$$

A simple rearrangement of total derivatives in S_H shows that

$$S_H = \int dx dz e^{-2d} R(H, d).$$

To prove gauge invariance, we can show that

$$Sg R = \hat{\mathcal{L}}_g R = g^M \partial_M R.$$

R is a generalized scalar.

(there is also a Generalized Ricci, but perhaps no generalized Riemann)

$$R|_{\tilde{d}=0} = R + 4(\square \phi - (\partial \phi)^2) - \frac{1}{12} H^2$$

This is the combination of familiar scalars that is an $O(D,D)$ invariant generalized scalar!

THE END