

Understanding your network towards interpretability in machine learning applications in many-body physics

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- systems) & characterizing phases Original work: Carrasquilla & Melko, Nature Physics 13 (2017)
- 3) Neural network quantum states
 - Representation learning the state
 - Finding ground states/dynamics Original work: Carleo & Troyer, Science 355 (2017)
- 4) Reinforcement learning
 - Quantum error correction/state control
 - Experiment design
- 5) Quantum machine learning See e.g. Biamonte et al., Nature 549 (2017)

Overview: Machine learning for quantum many-body physics

Recent review: Dawid et al., arXiv:2204.04198

1) Phase classification: supervised/unsupervised (+ many different physical

2) Interpretability (analysis of bottlenecks, (symbolic) regression, CCNN

architecture, Hessian based approach,...) See e.g. Dawid et al., Mach. Learn.: Sci. Technol. 3 (2021)

Review: Torlai & Melko, Annu. Rev. Condens. Matter Phys. (2020)

See e.g. Melnikov et al., PNAS 115 (2017)





What problems are we trying to solve

Some (interesting) model with some tuning parameter

- (quantum) magnetism
- Topological transition
- Non-equilibrium dynamics
- Characterize a quantum system

- Spin configurations
 - observables
- Quantum states
- Entanglement spectra
- . . .

. . . Some Input

Some (machine learning) method

• Expectation values of

- Supervised and unsupervised methods
- Different neural network architectures
- Support vector machines

. . .









2D Ising model at finite temperature Input: spin configurations Method: fully connected neural network



Carrasquilla & Melko, Nature Physics 13 (2017)

Machine learning phases of matter

1D Kitaev chain Input: entanglement spectra Method: learning by confusion (with neural net)











Mott insulator to superfluid transition Input: QMC configurations from SSE Method: convolutional neural network



Dong et al., PRB 99 (2019)

Machine learning phases of matter

Many-body localization Input: eigenstates of the Hamiltonian Method: Adversarial training (two neural nets)



Huembeli et al., PRB 99 (2019)

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Machine learning phases of matter

Input: experimental time of flight images Method: convolutional neural network



Rem et al., Nature Physics 15 (2019)



Annabelle Bohrdt

Topological phase diagram of Haldane model







Interpretability

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Different routes to interpretability



Annabelle Bohrdt

An incomplete and biased overview

- Directly looking at weights
- Bottleneck based approach
- Support vector machines
- Hessian based approach
- Taylor expansion type approach Correlator convolutional neural network





Looking at weights











Image: Dawid et al., arXiv:2204.04198

Looking at weights





Analyzing network weights



Problem: pre-processing of input data, need a priori physical insights for feature selection

Non-linear dependence on input => Introduce non-linearities in input to regain linear dependence

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2D Fermi-Hubbard @ finite doping: charge



Khatami et al., PRA 102 (2020) Broblem:, non-diperation structure correlations which cannot be visualized this way

Convolutional neural networks: looking at filters

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Bottleneck based approach









$$L(x_{in}, x_{out}) = |x_{in} - x_{out}|^2$$

problem: assumes that we already know which dependence to look for —> we can only compare it against the quantities or features we suspect to be important.

Bottleneck-based approach

2.0

(a)

spin configurations of 2D Ising model

0

ordered phase

unordered phase







One possibility: symbolic regression on the latent space



Goal: Functional form to relate physical input parameters to latent vector z

Miles et al., PRB 104 (2021)

Bottleneck-based approach



One possibility: symbolic regression on the latent space

- Here: one-particle Anderson impurity model spectral functions
- Use genetic algorithm to obtain functional form

Miles et al., PRB 104 (2021)

More on symbolic regression (using neural nets): Feynman AI: Udrescu & Tegmark, Sci. Adv. 6 (2020)

Symbolic regression



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Quantum state tomography





Iten et al., PRL 124 (2020)

Bottleneck-based approach

Training using question neuron: Input: observations, question, correct answer



Heliocentric solar system











- all useful data stored in representation in compact form
- Comparison to hypothesis possible (if hypothesis exists)
- insights possible from the number of required parameters
- insights from change in the representation when manually changing the input, and the change in output when manually changing the representation

Iten et al., PRL 124 (2020); review on AI physicists: Wu & Tegmark, PRE 100 (2019)

Bottleneck-based approach

Training using question neuron: Input: observations, question, correct answer





Siamese neural network: classify same vs different t



Polynomial regression on bottleneck layer

Wetzel et al., PRR 2 (2020)

Bottleneck-based approach



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Support vector machines









Image: wikipedia

Support vector machines

Want to minimize (optimization with constraints: maximize margin while classifying correctly):

$$L = \frac{1}{2} |\theta|^2 - \sum_{i=1}^n \alpha_i [y_i (\theta^{\mathsf{T}} x_i + \theta_0) - 1]$$
rse margin
It to maximize gin)
$$\mathcal{L}_{i=1} \int_{\mathbf{L}_{i=1}}^{\mathbf{L}_{i=1}} \int_{\mathbf{L}_{i=1}}^{\mathbf{L}_{i=1}} \mathcal{L}_{i=1} \int_{\mathbf{L}_{i=1}}^{\mathbf{L}_$$

Dual formulation:

$$L_D = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^\mathsf{T} x_j \quad \text{subject to } \alpha_i \ge 0$$

See e.g. Murphy, Machine Learning: A Probabilistic Perspective (MIT Press, Cambridge, 2012) in many-body physics: Ponte & Melko, PRB 96 (2017); review: Dawid et al., arXiv:2204.04198 ASC summer school 2022 21





•	,	n
•	,	n







Image: wikipedia

Support vector machines

Want to optimize:

$$L_D = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^\mathsf{T} x_j \quad \text{subject to } \alpha_i$$

Introducing a feature map (Kernel trick):

$$L_{D} = \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} \left\langle \Phi(x_{i}), \Phi(x_{j}) \right\rangle$$

$$P + x_{2}^{2}$$
More applications: Greitemann et al.,

See e.g. Murphy, Machine Learning: A Probabilistic Perspective (MIT Press, Cambridge, 2012) in many-body physics: Ponte & Melko, PRB 96 (2017); review: Dawid et al., arXiv:2204.04198 ASC summer school 2022 22

99 (2019); Liu et al., PRR 3 (2021), ...





PRB



SVM decision function vs squared magnetization



Ponte & Melko, PRB 96 (2017)

SVM: example

Spin configurations 2D Ising model

Polynomial kernel $K(\sigma, \sigma') = (\sigma \cdot \sigma')^k$



Linear decision boundary (k=1) not enough to distinguish FM (m = +-1) and paramagnet (m = 0)







Hessian-based approach







- Independent of ML architectures
- Influence function: indicates which training points are influential for a chosen (test) prediction. Analysis of the most influential examples can reveal the characteristics which impacts

the machine learning predictions.

- Resampling uncertainty estimation: check whether there are training samples similar to test sample & how big/small errors are on this training data
- Extrapolation: explore flat basin around minimum, make predictions for the same test point, calculate variance of the test loss

Dawid et al., Mach. Learn.: Sci. Technol 3 (2022)

Hessian-based approach







OP Publishing

Phase transition less/more sharp for L=12/14



Dawid et al., Mach. Learn.: Sci. Technol 3 (2022)

Hessian-based approach





Correlator convolutional neural network





Setting the stage: quantum simulation

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Setting the stage: Projective measurements

Annabelle Bohrdt



averaging



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Setting the stage: Projective measurements





Setting the stage: Projective measurements

Annabelle Bohrdt



Mazurenko et al., Nature 545 (2017)





Setting the stage: Fermi-Hubbard model

Annabelle Bohrdt



$$\sum_{\langle i,j\rangle,\sigma} \left(\hat{c}_{i,\sigma}^{\dagger} \hat{c}_{j,\sigma} + h.c. \right) + U \sum_{i} \hat{n}_{i,\uparrow} \hat{n}_{i,\downarrow}$$

$$funneling \qquad function$$





Setting the stage: Candidate theories

Annabelle Bohrdt

Geometric string theory

Grusdt et al., PRX 8 (2018), Grusdt et al., PRB 99 (2019), Bohrdt et al., NJP 22 (2020)

Early work: Bulaevskii et al., JETP 27 (1968), Trugman, PRB 37 (1988), Manousakis, PRB 75 (2007)

P. W. Anderson, Science 235, 1196 (1987)

Setting the stage: snapshots

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Training a neural network

Bohrdt et al., Nature Physics 15 (2019)

Evaluating experimental data

- Descriptions for the 1D t-J model
- Convolutional neural network: varying the filter size

Problem: many correlation functions possible in given filter (in 2D!)

Bohrdt et al., Annals of Physics (2021)

Looking at filters

- Looking at filters difficult: non-linearity mixes all orders of correlations
- Non-linearity necessary: otherwise, network corresponds to function that multiplies the input by a weight matrix and adds to it an additional bias vector.

Interpretability?

Typical activation function: rectified linear unit

Miles et al., Nature Comm. 12 (2021) See also: Wetzel & Scherzer, PRB 96 (2017)

Correlator convolutional neural network

With fixed filters, re-train back portion of the network with loss:

 $L_{\text{path}}(y,\hat{y}) \equiv -y \log \hat{y} - (1-y) \log (1-\hat{y}) + \lambda \sum_{\alpha,n} |\beta_{\alpha}^{(n)}|$

Miles et al., Nature Comm. 12 (2021)

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Miles et al., Nature Comm. 12 (2021)

Correlator convolutional neural network

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Miles et al., Nature Comm. 12 (2021)

Higher-order correlations

Example Filter

Miles et al., Nature Comm. 12 (2021)

From filter to correlation

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TAS

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Miles et al., Nature Comm. 12 (2021)

Higher-order correlations

(a) Staggered magnetization.

Histograms of pattern occurrence

Ο

0.0075 0.0100 0.0125 0.0150 0.0175 0.0200

CCNN: Application 2

Lukin et al., Science 364 (2019)

Non-equilibrium dynamics

Initial state: $E_i = \langle \psi_0 | \hat{H} | \psi_0 \rangle$

 $E_i =$

Non-equilibrium dynamics

Thermal density matrix:

$$\hat{\rho}_{\beta} = \frac{1}{Z} \exp(-\beta_{\text{eff}} \hat{H})$$

$$\beta_{\text{eff}} = 1/T_{\text{eff}}$$

$$\operatorname{tr}\left(\hat{H}\hat{\rho}_{\beta}\right)$$

Dynamics

Equilibrium

Non-equilibrium dynamics

 10^{2}

Output

 10^{1} 50

Bohrdt et al., PRL 127 (2021)

Non-equilibrium dynamics

Non-ecuilibri im dynamics

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Bohrdt et al., PRL 127 (2021)

Non-equilibrium dynamics

order of correlations taken into account

CCNN: Application 3

Miles et al., arXiv2112.10789

Rydberg system phase diagram

Thanks for your attention!

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Bonus slides

Miles et al., Nature Comm. 12 (2021)

CCNN: symmetric convolutions

